Astera SBi3 Pro+ Ruggedized GNSS/INS receiver for integrated solutions, ready for sensor fusion











AsteRx SBi3 Pro+ GNSS/INS multi-frequency receiver delivers reliable centimeter level positioning together with 3D orientation in challenging environments. Thanks to the built-in inertial sensor, it provides orientation (heading, pitch and roll) as well as dead reckoning making it ideal for systems that require positioning under any condition. This housed highperformance GNSS/INS system is ideal for rapid integration into machine control or ground robotic applications. AsteRx SBi3 Pro+ is the most flexible boxed GNSS/INS solution, offering full access to raw GNSS and INS data as well as allowing multiple antenna configurations.

KEY FEATURES

- Accurate and reliable IMU-enhanced GNSS positioning down to centimeter level
- Full access to raw GNSS and IMU data
- Heading with single or dual GNSS antenna
- Pitch and roll
- Robust and compact IP68 weatherproof housing
- AIM+ Advanced Interference Mitigation technology, as part of the GNSS+ algorithm suite

Reliable and robust

The AsteRx SBi3 Pro+ is a state-of-the-art GNSS/INS rover receiver designed to provide robust and reliable positioning and 3D attitude in the most challenging environments. Septentrio's multi-constellation, multi-frequency, accurate and reliable RTK is enhanced by a powerful GNSS/INS integration accurately measuring heading, pitch and roll. While a single antenna allows a lean configuration, the dual antenna enables heading measurement without the need for movement. AsteRx SBi3 Pro+ features Advanced Interference Mitigation (AIM+) technology which can suppress the widest variety of interferers, from simple continuous narrowband signals to the most complex wideband and pulsed jammers.

Ideal for any integration

The AsteRx SBi3 Pro+ is not only delivering an already integrated position, but it also provides raw GNSS and IMU data, already synchronized and in a single data stream for customers that will integrate those components with other sensors for a larger data fusion system (i.e. lidar). Having GNSS and IMU hardware already integrated and data streams already synchronized will enable customers to focus on their own core technology without having to integrate GNSS and IMU sensors themselves.

Easy-to-integrate

The AsteRx SBi3 Pro+ delivers a full INS system on a single board for the maximum ease of hardware integration. Septentrio's web interface and software tools make it easy to integrate, configure and control the AsteRx SBi3 Pro+ receiver.

AsteRx SBi3 Pro+

FEATURES

GNSS signals

544 Hardware channels for simultaneous tracking of most visible signals:

- ▶ GPS: L1 C/A, L1C, L2C, L2 P, L5
- GLONASS: L1 C/A, L2C/A
- BeiDou: B1I, B2I, B3I
- ▶ Galileo: E1, E5a, E5b, E5 AltBOC
- SBAS: EGNOS, WAAS, GAGAN, MSAS, SDCM

Septentrio's patented GNSS+ technologies

- AIM+ unique anti-jamming and monitoring system against narrow and wideband interference with spectrum analyser
- IONO+ advanced scintillation mitigation
- APME+ a posteriori multipath estimator for code and phase multipath mitigation
- LOCK+ superior tracking robustness under heavy mechanical shocks or vibrations
- **RAIM+** (Receiver Autonomous Integrity Monitoring)

Formats

Septentrio Binary Format (SBF), fully documented with sample parsing tools NMEA 0183, v3.01, v4.0 RTCM v2.x, v3.x (MSM messages included) CMR v2.0 and CMR+

Connectivity

3 Hi-speed serial ports (RS232)
Ethernet port (TCP/IP, UDP, LAN 10/100 Mbps)
Power over ethernet
1 High-speed/full-speed USB device port
2 Event markers
FTP server
16 GB internal memory
NTRIP (client)

PERFORMANCE

Integrated position accuracy ^{1,2}

| | Horizontal | Vertical | |
|---------------------------------------|---------------------------|--------------------|--|
| Standalone | 1.2 m | 1.9 m | |
| SBAS | 0.6 m | 0.8 m | |
| DGPS | 0.4 m | 0.7 m | |
| RTK-INS 1,2,3 | | | |
| Horizontal accuracy | 0.6.0 | -m + 0 5 ppm | |
| Vertical accuracy | 1 | cm + 1 ppm | |
| Initialisation | | 7 s | |
| | 122 | | |
| Integrated attitude acc | Curacy 1,2,3 | DTK | |
| INOP | NRIK mode | RIK mode | |
| Heading, duai antenna | 0.3° | 0.15 | |
| Heading, single antenna | 0.3° | 0.2° | |
| Pitch/roll, dual antenna | 0.04* | 0.02* | |
| INS velocity 1,2,3 | | | |
| Nor | n RTK mode | RTK mode | |
| Velocity | 0.05 m/s | 0.02 m/s | |
| Position accuracy after | r outages ^{2, 8} | | |
| Outage (sec) | Horizontal | Vertical | |
| 5 | 0.1 m | 0.03 m | |
| 10 | 0.3 m | 0.05 m | |
| 30 | 3.0 m | 0.24 m | |
| | 2.8 | | |
| | Hooding | Ditch/Doll | |
| oulage (sec) | neauling 0.20 | | |
| 10 | 0.2 | 0.02 | |
| 20 | 0.2 | 0.04 | |
| 50 | 0.25 | 0.00 | |
| IMU performance | | | |
| Gyroscope performance | e | | |
| Input range | | + 500°/s | |
| Bias in-run instability | | 2.7°/hr | |
| Random walk / noise den | sity 0 | .15 - 0.2°/√hr | |
| Accelerometer perform | nance | | |
| Input range | | +8 g | |
| Bias in-run instability ⁴ | | 2.7 - 4.4 ug | |
| Random walk / noise den | sity ⁴ 17.0 | - 24.8 µg/√Hz | |
| | , | 10 | |
| Integrated position | | 200 Ц- | |
| Integrated position | | 200 HZ | |
| CNSS massuraments | | ~20 IIIS 2 LI-7 | |
| IMU row data | | 2 TZ 200 Uz | |
| IIVIO Taw uala | | 200 HZ | |
| Time precision | | | |
| xPPS out | | 5 ns | |
| Event accuracy | | < 20 ns | |
| Time to first fix | | | |
| Cold start ⁵ | | < 45 s | |
| Warm start ⁶ | | < 20 s | |
| Re-acquisition avg. | | avg 1 s | |
| Tracking performance (C/N0 threshold) | | | |
| Tracking | | 20 dB-Hz | |
| Acauisition | | 33 dB-Hz | |
| 1 | | | |

PHYSICAL AND ENVIRONMENTAL

| AsteRx SBi | |
|--|---|
| Size | 102 × 36 × 118 mm 4.0 × 1.4 × 4.6 in |
| Weight | 490 g / 17.3 oz |
| nput voltage | 4.5 to 36 VDC |
| Power consumption | |
| GPS/GLO L1/L2 | 1.3 W |
| All signals, all GNSS constellatior | ns 1.5 W |
| Connectors | |
| Antenna | 2 x TNC female |
| ETH | ODU 4 pins female |
| COM1/GPIO | ODU 7 pins female |
| PWR/USB/COM2/COM3 | ODU 7 pins female |
| Antenna(s) | |
| Output voltage | 5 VDC |
| Maximum current | 150 mA |
| Environment | |
| Operating temperature | -30° C to +65° C |
| | -22° F to +149° F |
| storage temperature | -40° C (0 +75° C |
| Humidity MIL-STD-810G Metho | d 507 5. Procedure I |
| Dust MIL-STD-810G, Metho | d 510 5. Procedure I |
| Shock MII -STD-810G. Method | 516.6. Procedure I/II |
| Vibration MIL-STD-810G, Metho | d 514.6, Procedure I |
| | |
| Certification | |
| ROHS, WEEE | |
| | |
| Open-sky conditions | |
| ² RMS levels | |
| ³ Baseline < 40 Km | |
| ⁴ Z-axis (lower value is for X & Y) |) |
| ⁵ No information available (no a | lmanac, |
| no approximate position) | |
| ⁹ Ephemeris and approximate p | position known |

- ^o Epnemeris and ap ⁷ 98% of samples
- ⁸ Relative to the last accuracy before outage





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